State of delivery

PDG3XROP…
PDE3XROP…

![State of delivery diagram]

**Operation steps**

1. ![Operation step 1 diagram]
2a. ![Operation step 2a diagram]
2b. ![Operation step 2b diagram]

**Electric current! Danger to life!**
Only skilled or instructed persons may carry out the following operations.

**Drill Location**
PDG3XROP…/ PDE3XROP…

**Drill bit** (7/32” or 5.5mm)

**0.55 Nm (5.0 lb-in)**

**Unit: inch**
3 PD3-4P

2c For 4 poles only
只适用于4极

2d P2
0.55 Nm (5.0 lb-in)

3 If Remote Operator was charged.
Only when the Remote Operator installation is complete, Button I can be pushed.

4 If Remote Operator was charged.
Only when the Remote Operator installation is complete, Button I can be pushed.

5 If Remote Operator was charged.
Only when the Remote Operator installation is complete, Button I can be pushed.

6 If Remote Operator was charged.
Only when the Remote Operator installation is complete, Button I can be pushed.
TRIP BUTTON POSITION

PD3 TMTU

PD3 ETU

unit: inch

TRIP LEVER – CHOOSE RIGHT POSITION

TMTU

ETU

7 PD3-3P

PD3-4P

P2

3 Nm (25 lb-in)

M5x120

P2

3 Nm (25 lb-in)

M5x120

8 TEST

Charged

Discharged

ON

OFF

Manual

Auto

Push to trip

\( \approx 8 \times \)
**TERMINAL**

![Terminal Diagram]

- Manual/Auto switch
- 3 x terminal connections
- Connections for Charged and Off

**CONNECTION**

![Connection Diagram]

- Circuit A
- Parallel connection between two remote operators
- Connections for L1 (L1+), N1 (L1-L2)

**Notes:**
- H = Signal lamp
- 0 = Pushbutton or contact for opening the circuit-breaker
- I = Pushbutton or contact for switch closing
- d = 4 – 8 mm
  (d = 0.16” – 0.31”)

**Technical Details:**
- 0.5 Nm
  (4.43 lb-in)
- 0.6 x 3.5
- 1 x 0.5 - 2.5 mm²
  1 x AWG20 - AWG12
- 1 x 0.5 - 2.5 mm²
  1 x AWG20 - AWG12
- 0.5 Nm
  (4.42 lb-in)
- 1 x 0.5 - 2.5 mm²
  1 x AWG20 - AWG12

**Website:**
www.eaton.com/recycling