



Agenda

- Drive will not start
- Drive will not get to speed
- 10 Common Fault codes
 - 1. Overcurrent
 - 2. Current limit controller
 - 3. Ground fault
 - 4. Output phase fault
 - 5. Overvoltage Fault
 - 6. Overvoltage controller
 - 7. Undervoltage fault
 - 8. Unit over temperature
 - 9. Motor over temperature
 - 10.Input phase fault



Drive does not start

Causes

- Drive not ready
- Drive not receiving a Run Signal

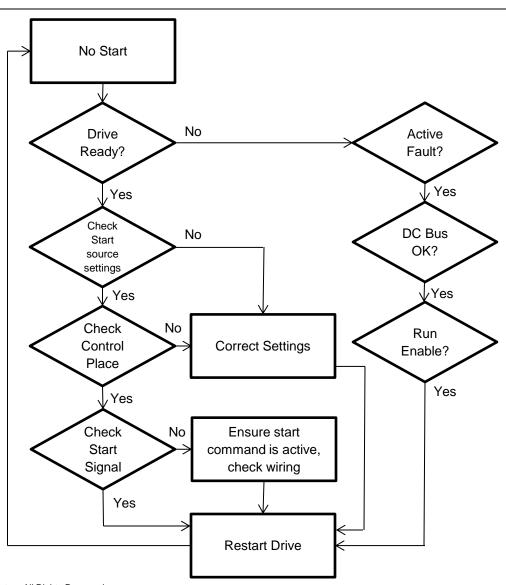
Not Ready Causes

- Active fault
- DC bus too high or low
- Run enable input not present

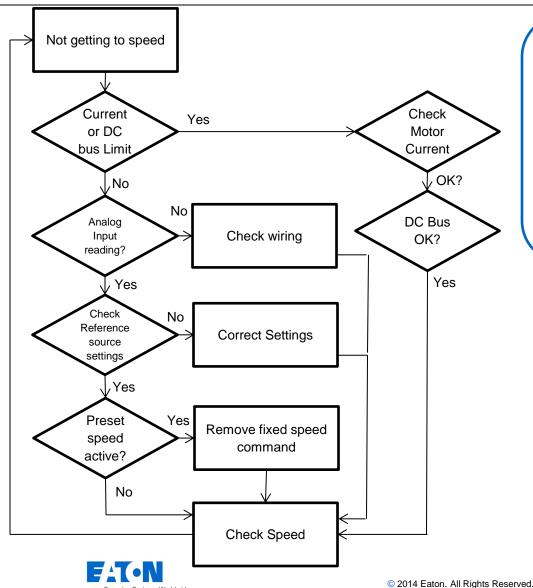
Run Signal not present

Control place not correct
 Example trying to start from I/O when active control place is keypad.





Drive does not get to speed



Causes

- Missing reference
- Preset speed or jog speed active

Missing Reference

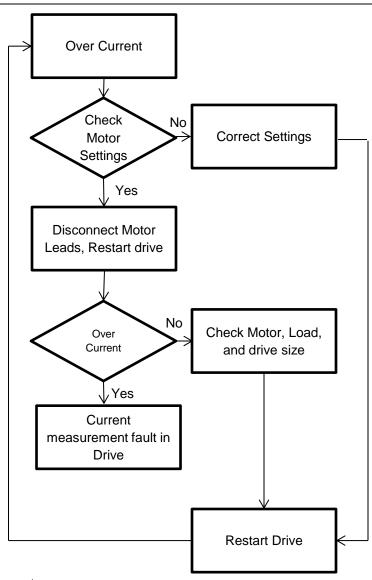
- Check analog input monitor
- Check that the drive is programmed to follow the correct input
- Ensure the drive is not hitting any other limits
- Check frequency reference compared to output frequency

10 Common Fault Codes - Overcurrent

<u>Causes</u>

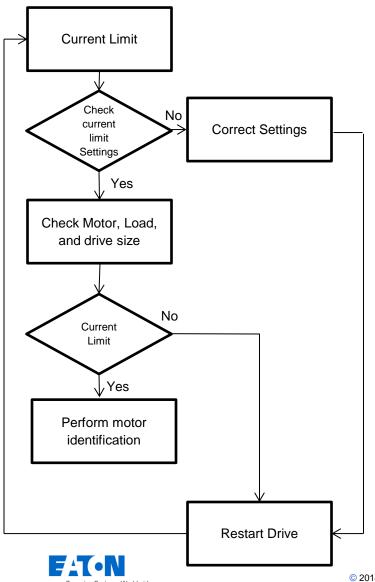
- Incorrect motor parameters
- Mechanical fault
- Electrical fault
- Current measurement error

- Check wiring and motor for insulation failures and proper connections
- Check for mechanical overload, Locked rotor
- Check for proper drive size





10 Common Fault Codes – Current Limit



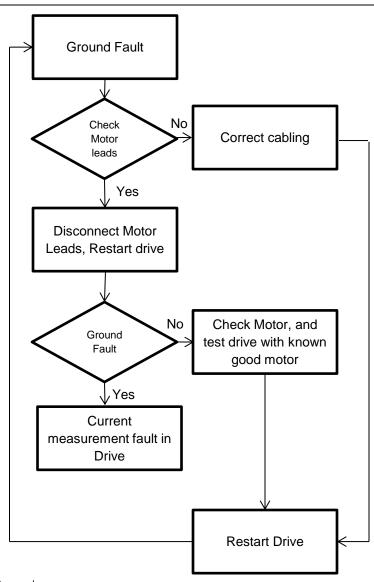
- Incorrect motor parameters
- Mechanical fault
- Electrical fault
- Current measurement error

- Not all models have an indication when the current limit is reached
- Current limit will reduce output frequency to reduce output current to at or below the current limit setting

10 Common Fault Codes – Ground Fault

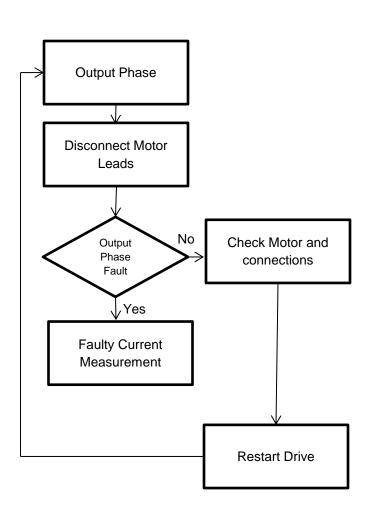
- Faulty motor
- Electrical fault
- Current measurement error

- Check for loose or high resistance connections to the motor
- Test motor for electrical failure
- Disconnect motor leads or apply known good motor to verify current measurements





10 Common Fault Codes – Output Phase



- Loose Motor Connections
- Faulty Motor
- Current measurement error

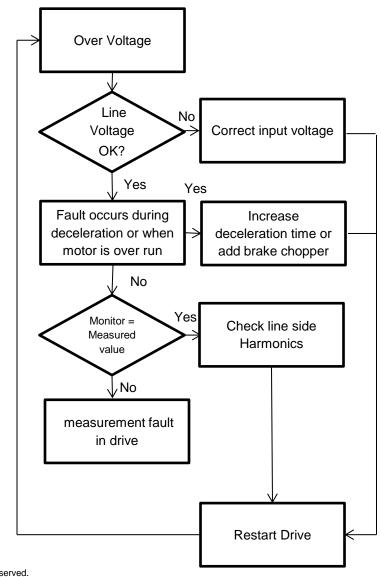
- Caused by current imbalance on the output of the VFD
- Look for loose connections or fault in motor windings



10 Common Fault Codes - Overvoltage

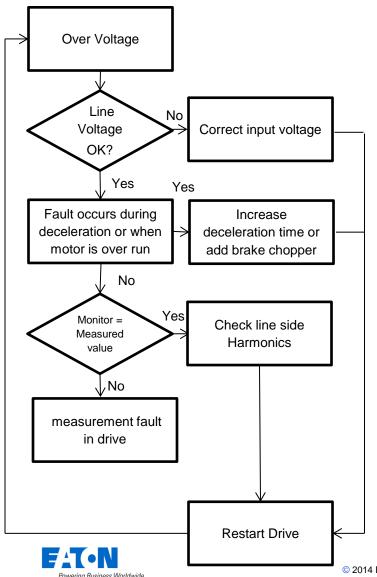
- High Line Voltage
- Regenerated voltage from load
- Excessive line side harmonics

- If Fault occurs during deceleration or stop command then increase deceleration time or brake chopper may be needed.
- Cyclic loads may need regen unit or brake chopper.
- Excess harmonics may be overcharging DC link capacitors.





10 Common Fault Codes – Overvoltage Controller



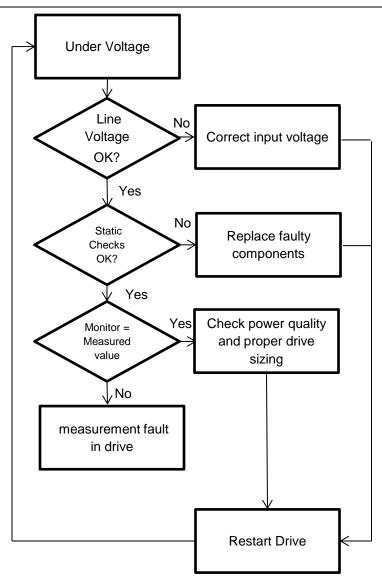
- High Line Voltage
- Regenerated voltage from load
- Excessive line side harmonics

- Trouble shooting is the same as for the overvoltage fault, the overvoltage controller will increase the reference in an attempt to bleed off excess voltage
- Not all series of VFD's have an indication of when this controller is active.

10 Common Fault Codes – Undervoltage

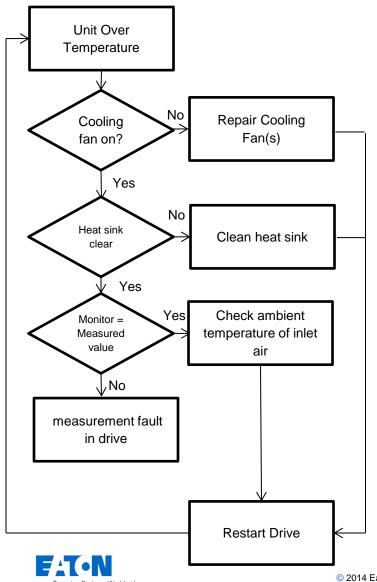
- Low Line Voltage
- Improperly sized drive

- Check for low line voltage or drops in line voltage under load.
- Check for damaged input rectifiers with static checks
- Check for even current draw on input when drive is running





10 Common Fault Codes – Unit Over temp



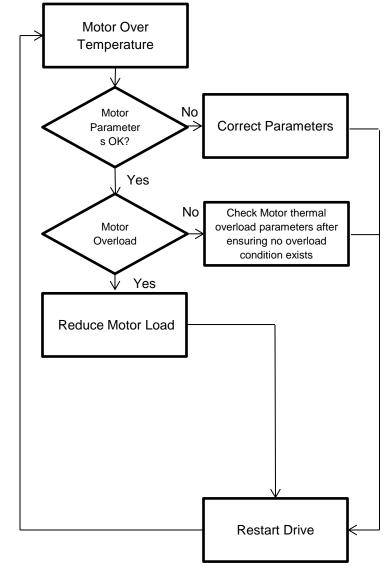
- High Ambient temperature
- Insufficient airflow
 - Plugged heat sink
 - Failed cooling fan

- Check Main cooling fan for rotation
- Ensure unobstructed heat sink and airflow
- Check ambient temperature is below the drives ratings

10 Common Fault Codes – Motor Over temp

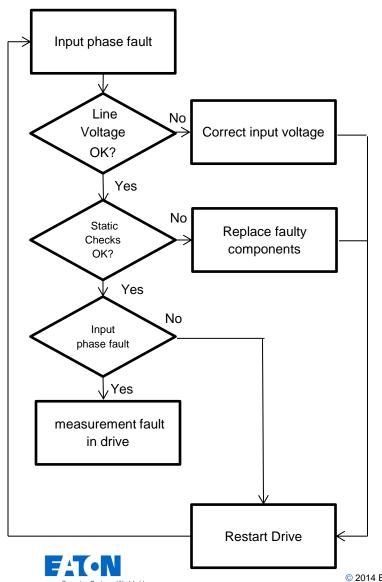
- Overloaded Motor
- Operating Motor at high load at low speeds
- Undersized Motor
- Incorrect Motor Parameters

- Check Motor Parameters
- Observe current and speed
- Current should be nearly proportional to speed, if running half speed at FLA drive will protect motor from increased thermal stress from reduced cooling





10 Common Fault Codes – Input Phase



- Missing Input phase
- Damaged Drive

- Check for Line Voltage imbalance
- Check for loose connections or blown fuses
- Check for damaged input rectifiers with static checks
- Single phase input drives need to have this protection disabled
- Check for even current draw on input when drive is running

